SERIES 50A-DD PWM BRUSH TYPE SERVO AMPLIFIERS Models: 30A8DD, 25A20DD, 50A8DD, 50A20DD

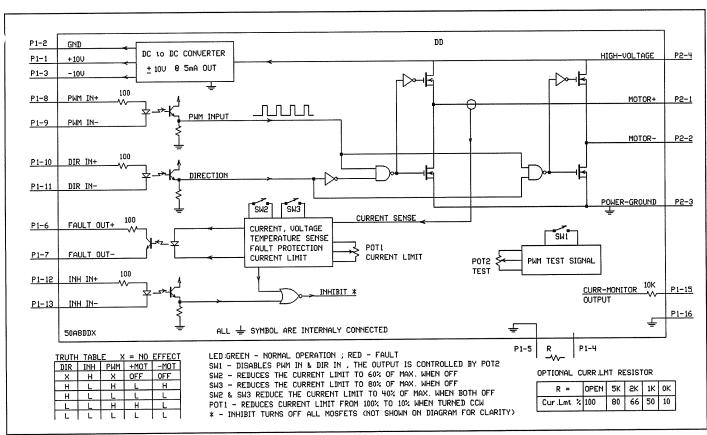
FEATURES:

- * Surface-mount technology
- * Small size, low cost, ease of use
- * Optically isolated digital inputs
- * Adjustable current limit
- * Built-in PWM generator for self-test
- * Four quadrant regenerative operation





DESCRIPTION: The 50A-DD Series PWM servo amplifiers are designed to drive brush type DC motors. The PWM frequency is determined by the PWM input signal. All models are fully protected against over-voltage, over-current, over-heating and short circuits across motor, ground and power leads. All models interface with digital controllers that have a digital PWM output. They can also be used as a stand-alone system when using Pot 2. The 50A-DD Series amplifiers require only a single unregulated DC power supply as all logic and control voltages are generated internally. PWM input determines the output duty cycle. "Direction In" determines which side of the "H bridge" output is switching. Current limit can be reduced by Pot 1 (14 turn potentiometer), by DIP the switches and/or by an external current limiting resistor. The voltage at the current monitor pin P1-15 is proportional to the actual motor current.



	MODELS				
POWER STAGE SPECIFICATIONS	30A8DD	25A20DD	50A8DD	50A20DD	
DC SUPPLY VOLTAGE	20 - 80 V	40 - 190 V	20 - 80 V	40 - 190 V	
PEAK CURRENT (2 sec. max., internally limited)	± 30 A	± 25 A	± 50 A	± 50 A	
MAXIMUM CONTINUOUS CURRENT (internally limited)	± 15 A	± 12.5 A	± 25 A	± 25 A	
MINIMUM LOAD INDUCTANCE*	150 µH	250 µH	150 µH	250 µH	
SWTCHING FREQUENCY	5 - 45 KHz				
HEATSINK (base) TEMPERATURE RANGE	-25° to +75° C, disables if > +75° C				
POWER DISSIPATION AT CONTINUOUS CURRENT	25 W	55 W	45 W	115 W	
OVER-VOLTAGE SHUT-DOWN (self reset)	85 V	195 V	85 V	195 V	

MECHANICAL SPECIFICATIONS			
POWER CONNECTOR	Screw terminals		
SIGNAL CONNECTOR	Molex connectors		
SIZE	7.35 x 4.40 x 1.00 inches		
	186.7 x 111.7 x 25.4 mm		
WEIGHT	1.5 lb.		
	0.68 kg		

^{* &}quot;Pancake" and "basket-wound" motors require external inductors.

PIN FUNCTIONS

CONNECTOR	PIN	NAME	DESCRIPTION / NOTES	1/0
-	1	+10V @ 5 mA OUT	For customer use	0
	2	Gnd	Reference ground	GND
	3	-10V @ 5 mA OUT	For customer use	0
	4	CURRENT LIMIT	Can be used to reduce the factory-preset maximum current limit .	I
	5	GND	Ground for Current Limit Resistor	GND
	6	+FAULT	Opto isolated. Output transistor turns on and becomes high during output short circuit, over voltage, over temperature, inhibit,	0
P1	7	-FAULT	and during power-up reset. Fault condition indicated by red LED.	
	8	+PWM	Pulse Width Modulated Input, opto-coupled	I
	9	-PWM		
	10	+DIR	Direction Input, opto-coupled	I
	11	-DIR		
	12	+INHIBIT	Inhibit Input, opto-coupled	1
	13	-INHIBIT	Pull low to enable	
	14	NC		
	15	CURRENT MONITOR	This signal is proportional to the actual current in motor leads. Scaling is 1V = 4A, full scale.	0
	16	GND	Current Monitor Ground	GND

CURRENT LIMITING

Current limit can be reduced by Pot 1 (14 turn potentiometer), by the DIP switches and/or by an external current limiting resistor. See functional block diagram. The voltage at the current monitor pin P1-15 is proportional to the actual motor current.

ORDERING INFORMATION

Models: 30A8DDX, 25A20DDX, 50A8DDX, 50A20DDX

X indicates the current revision letter.

MOUNTING DIMENSIONS:

